		EAG! Searci				
L21	14643	jaw & item grasp\$4 & leverage & force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 16:26
L22	111	jaw & item & grasp\$4 & leverage & force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 16:26
L23	1	jaw & item & grasp\$4 & leverage & force & drive near cable	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 16:27
L24		("2475041" "2709570" "3193908" "3208134" "3529497" "3576064" "3781023" "4078766" "4144868" "4231581" "4482132" "4624323" "4637113" "4637538" "5141205" "5188159" "5370192" "5433005" "5957429" "6308934" "D272712" "D292368" "D377302").PN. OR ("6695288").URPN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/08/30 16:30
L25	17	("0293848" "0430768" "0823367" "1879452" "1915404" "1944116" "2324415" "2439785" "4538485"). PN. OR ("6601479").URPN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/08/30 16:37
L26	0	600/109.ccls. & end near effector & drive near mechanism & electronic near controller	US-PGPUB; USPAT; USOCR	OR	ON	2006/08/30 16:38
L27	0	600/118.ccls. & end near effector & drive near mechanism & electronic near controller	US-PGPUB; USPAT; USOCR	OR	ON	2006/08/30 16:38
L28	0	600/114.ccls. & end near effector & drive near mechanism & electronic near controller	US-PGPUB; USPAT; USOCR	OR	ON	2006/08/30 16:39
L29	0	606/147.ccls. & end near effector & drive near mechanism & electronic near controller	US-PGPUB; USPAT; USOCR	OR	ON	2006/08/30 16:39
L30	0	606/208.ccls. & end near effector & drive near mechanism & electronic near controller	US-PGPUB; USPAT; USOCR	OR	ON	2006/08/30 16:39

L31	0	606/148.ccls. & end near effector & drive near mechanism & electronic	US-PGPUB; USPAT;	OR	ON	2006/08/30 16:39
		near controller	USOCR			

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Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	58	("2765930" "3111230" "3190286" "32 66059" "3497083" "3659890" "375956 3" "3782666" "4495423" "4887612" " 4977886" "5171258" "5209747" "5238 005" "5254130" "5347987" "5354311" "5395367" "5431675" "5467763" "54 78347" "5478351" "5497784" "552064 4" "5607450" "5618294" "5620415" " 5643294" "5746759" "5766196" "5823 993" "5826467" "5845646" "5919206" "5964780" "5977886" "6004332" "60 19780" "6042166" "6058323" "606610 2" "6080181" "6102920" "6132441" " 6143005" "6165184" "6214028" "6223 100" "6233474" "6244644" "6332889" "6358268").PN.	US-PGPUB; USPAT; USOCR; FPRS	OR	ON	2006/08/30 15:58
L2	293	medical near instrument & first near jaw with pivot near joint & second near jaw with pin & slot & drive mechanism with linkage & electronic near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:28
L3	293	robot\$6 near control\$4 near medical near instrument & first near jaw with pivot near joint & second near jaw with pin & slot & drive mechanism with linkage & electronic near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:44
L4	1	robot\$6 near control\$4 near medical near instrument & first near jaw with pivot near joint & second near jaw with pin & slot & drive near mechanism with linkage & electronic near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:45
L5	0	robot\$6 near control\$4 near medical near instrument & first near jaw & second near jaw & drive near mechanism with accomodating near mechanism & locked near position & electronic near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:47

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L6	1	position\$4 near2 item & first near jaw & second near jaw & grasp near2 item & increase near force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:50
L7	0	drive near mechanism & increasw near force & jaw near member & (electronic or robotic) near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:51
L8	1	drive near mechanism & increase near force & jaw near member & (electronic or robotic) near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON .	2006/08/30 15:52
L9	993	(606/1).CCLS.	USPAT	OR	OFF	2006/08/30 15:53
L10	0	606/1.ccls & jaw & drive near mechanism & (robotic or electronic) near controller	USPAT	OR	OFF	2006/08/30 15:54
L11	0	606/1.ccls & jaw & drive near mechanism & (robotic or electronic) near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:55
L12	0	606/130.ccls & jaw & drive near mechanism & (robotic or electronic) near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:55
L13	0	600/37.ccls & jaw & drive near mechanism & (robotic or electronic) near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:55

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L14	0	606/205.ccls & jaw & drive near mechanism & (robotic or electronic) near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR ,	ON	2006/08/30 15:55
L15	0	606/206.ccls & jaw & drive near mechanism & (robotic or electronic) near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:55
L16	0	606/207.ccls & jaw & drive near mechanism & (robotic or electronic) near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:56
L17	2209	(grip\$4 or grasp\$4) & (robotic\$4 or electronic or electrical) near controller	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 16:00
L18	51	(grip\$4 or grasp\$4) & (robotic\$4 or electronic or electrical) near controller & jaw & drive near mechanism	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 16:19
L19	24	(grip\$4 or grasp\$4) & (robotic\$4 or electronic or electrical) near controller & end near effector & drive near mechanism	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 16:24
L20	2778	jaw & suture & force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 16:25